

### **AHRS1000**

#### High Performance Attitude and Heading Reference System



### **Main Features**

- 3-axis Attitude Angle Accuracy: 0.5° (static), 2° (dynamic)
- Attitude Angle Range: yaw ±180°, pitch ±90°, roll ±180°
- Range: Acc ±5g, Gyro ±300°/s, Magnetic ±6gauss
- Bandwidth: 200Hz, Sampling Rate: 5000 samples/s
- Data Storage Capacity: 8GB
- Wide Working Temperature: -40°C~+85°C
- High Stability & Reliability, High Survivability

AHRS1000 Attitude and Heading Reference System (AHRS) is a high performance inertial measurement system, it can measure 3-axis attitude angles (yaw, pitch, roll) for the strap-down carrier. No matter the carrier is moving or static, AHRS1000 can work stably and provide highly precise attitude angles. Each X, Y, Z axis of AHRS1000 is composed of one accelerometer, one gyro, one magnetic sensor. the gyro can provide the accurate 3-axis angular rate, the accurate 3-axis attitude angles can be calculated according to strap-down algorithm, the magnetic sensor and accelerometer can amend the attitude angles continously, it can realize dynamic error compensation through Kalman filter and complementary filter methods.

In full temperature range (-45°C~+85°C), it adopts digital signal processor (DSP) to adjust, compensate (zero position, installation error), layout of strap-down navigation system and attitude angle calculation, etc. The system enjoys small size, light weight, it is widely applied in Unmanned Aircraft, Precision Guided Weapon, ROV Underwater Navigation, Ship Stability & Control, etc.

- √ 12-Step Quality Control, Super Reliability, More **Functions**
- ✓ Adopting Original Big Brand Component, High-class **Material, Competitive Price**
- ✓ Real Actual Precise after Calibration, Perfect **Performance**
- Successful Applications in Tens of Fields, More than 1000 Customers are Using

### Typical Applications



**Unmanned Aircraft** 



Precision Guided Weapon



**ROV Underwater Navigation** 



Ship Stability & Control

**MEMS Acc** INS

E-compass

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## **AHRS1000**

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# **Technical Specifications**

Technical Specs			
Item		Specs	Value
System General Specs		Startup time	<1s
		Output mode	speed, position, attitude, angular rate, acceleration
		Bandwidth	200Hz (settable)
		Data storage capacity	8GB
		Sampling rate	5000samples/s
Heading and Attitude Parameters	Yaw	Range	±180°
		Static accuracy	0.5°
		Dynamic accuracy	2° (RMS)
	Pitch	Range	±90°
		Static accuracy	0.5°
		Dynamic accuracy	2° (RMS)
	Roll	Range	±180°
		Static accuracy	0.5°
		Dynamic accuracy	2° (RMS)
Gyro		Range	±300°/s
		Bias stability	200°/h
		Resolution	0.05°/s
		Bandwidth	40Hz
		Output noise	0.2°/s
Accelerometer		Range	±5g
		Non-linearity	<5%
		Resolution	0.001g
		Bandwidth	40Hz
		Output noise	0.5mg
Magnetic Sensor		Range	±6Gauss
		Output noise	0.5mg
		Bandwidth	40Hz
		Non-linearity	<1%
Electrical Characteristics		Power supply	5.7~16VDC
		Current	300mA
		Output interface	RS232
		Connector	9-pin D model connector
Physical Characteristics		Weight	280g
		Dimension	60*60*60mm
Environment Characteristics		Workning temperature	-40° C~+85°C
		Shock	200g, 6ms