High Performance Single Axis Closed Loop MEMS Capacitive Accelerometer



Main Features

- Range: ±2g, Excellent Bias Stability: 0.03mg
- Output: Differential Output / Single-Ended Output
- Very Low Noise: $0.9\mu g/\sqrt{Hz}$ for $\pm 2g$ Range (typ)
- Input Power Supply: 4.75~5.25V
- Embedded Self-Test Function and Temperature Sensor
- Embedded Precision Reference Voltage
- Shock Survivability: 6000g, Vibration Resistance
- Wide Operating Temperature Range: -40~+125°C

MA1002A MEMS accelerometer is the best high performance capacitive accelerometer adopting closed loop structure, it uses high performance ASIC and MEMS sensor to build closed-loop system, and it enjoys exercellent performance with low noise, dynamic range, non linearity, repeatability, temperature drift and shock resisitance. MA1002A guarantees confident and accurate vibration measurement in rugged environments.

MA1002A accelerometer also has embedded self test function, temperature sensor for compensation and built-in high precision reference voltage, which ensures MA1002A to be the top level of accelerometer around the world. Using tiny sealed LCC20 encapsulation (9*9mm), MA1002A has been widely used in Seismic Monitor, Inertial Navigation, Industrial Contorl, Platform Stabilization, Avionics, UAV systems, and Motion Control, etc. Each accelerometer is fully tested and gualified, and its super reliability and excellent performance gains customers' high praise.

- ✓ 12-Step Quality Control, Super Reliability, More **Functions**
- ✓ Adopting Original Big Brand Component, High-class **Material, Competitive Price**
- ✓ Real Actual Precise after Calibration, Perfect Performance
- Successful Applications in Tens of Fields, More than 1000 Customers are Using

Typical Applications



Seismic Monitor



Railway Technology



Monitoring & Control



Structure Health Monitor

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MEMS Gyro GNSS/INS

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Vertical Gyro AHRS Inclinometer FOG

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Technical Specifications

Technical Specs (Test condition: Vcc=5V, 25°C, Differential Output)							
Parameter	Comments	Min	Тур.	Max	Unit		
Accelerometer							
Range		-	±2	-	g		
Non linearity	IEEE Norm , % of full scale		0.1	0.3	%		
Frequency Response	±5% bandwidth	100	-	-	Hz		
Frequency Response	±3dB bandwidth	1000	-	-	Hz		
Resonant Frequency		-	3.0	-	kHz		
Resolution	1Hz		7	-	μg		
Noise Spectral Density	In band [0.1Hz~100Hz]	-	10.1	-	µgrms		
	@0.1Hz	-	3.0	-			
	@1Hz	-	1.7	-	µg/√Hz		
	@10Hz	-	1.0	-			
	@100Hz	-	0.9	-			
Bias							
Zero Calibration		-8	-	+8	mg		
Temperature Coefficient		-0.2	-	0.2	mg/°C		
Stability	1 hour, 1σ	-	0.03	0.08	mg		
Repeatability		-	0.15	0.40	mg		
Scale Factor							
Scale Factor		1782	1800	1818	mV/g		
Temperature Coefficient		-	50	80	ppm/°C		
Stability	1σ#1	-	50	120	ppm		
Repeatability		-	50	120	ppm		
Axis Misalignment							
Input Axis Misalignment (Kp,Ko)		-	-	10	mrad		
Self Test							
Frequency	Square wave output	-	19	-	Hz		
Duty Cycle		-	50	-	%		
Amplitude	Peak to peak	-	0.28	-	g		
STEN Input Threshold Voltage	High level is valid	0.8	-	-	Vcc		

#1 The test method of scale factor stability: after power on the chip for 1 minute, then start to test the scale factor, and then test the scale factor every half hour, and test 7 times, and calculate the standard deviation for these 7 scale factors.

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AHRS

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Technical Specifications

Technical Specs (Continued)							
Parameter	Comments	Min	Тур.	Max	Unit		
Temperature Sensor							
Output Voltage	@25°C	-	2.47	-	V		
Sensitivity		-	8.3	-	mV/°C		
Output Current Load		-	-	20	uA		
Output Capacitive Load		-	-	30	pF		
Reset							
RSTN Input Threshold Voltage	Low level valid	-	-	0.2	Vcc		
Power Supply (Vcc)							
Input Voltage		4.75	5	5.25	V		
Running Current Consumption		-	5.4	-	mA		
Startup Time	Turn on or RSTN pull-up	-	10	-	ms		
Accelerometer Output							
Output Voltage	Full range differential output	-	±3.6	-	V		
Resistance Load		10	-	-	kΩ		
Capacitive Load		-	-	30	pF		

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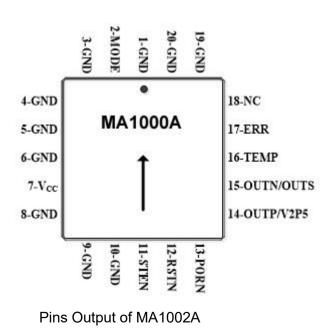
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Pins Definition

Pins Definition of MA1002A					
Pins No.	Pins Name	Definition	Description		
1, 3, 4, 5, 6, 8, 9, 10, 19, 20	GND	connect to ground	power ground		
2	MODE	digital input	select output mode (low level is differential output mode, high level is single ended output mode, default is inner drop down mode)		
7	Vcc	power	5V power input		
11	STEN	digital input	self test input, default inner drop down, seft test is valid when it is high level		
12	RSTN	digital input	external reset input, default inner pull up, low level reset is valid		
13	PORN	digital output	power on reset output, the output is high when the power voltage is stable		
14	OUTP/V2P5	analog output	differential output positive/2.5V reference voltage output		
15	OUTN/OUTS	analog output	differential output negative/single-ended output		
16	TEMP	analog output	temperature sensor output		
17	ERR	digital output	self test output or system fault output		
18	NC	-	no connection		

Pins Figure



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Absolute Max. Ratings

Absolute Maximum Ratings					
Parameter	Minimum	Maximum	Description		
Power Supply	-0.3V	5.8V			
Pins' voltage	-0.3V	Vcc+0.3V			
Working Temperature	-40°C	+125°C			
Storage Temperature	-55°C	+150°C			
Vibration Resistance	-	6.06g	MA1002A/MA1003A, random, with power on [20, 2000Hz], X, Y, Z axis, each axis 15minutes		
	-	20g	MA1010A/MA1030A,random, with power on [20, 2000Hz], X, Y, Z axis, each axis 15minutes		
Shock Resistance	-	6000g	3 times/axis, 0.15ms, half sine wave, $\pm X$, $\pm Y$, $\pm Z$ axis		
	-	1500g	3 times/axis, 0.5ms, half sine wave, $\pm X$, $\pm Y$, $\pm Z$ axis		
ESD Level	-2kV	2kV	HBM mode		

Remarks: the accelerometer that works long time in absolute maximum ratings may influence the reliability.

Handling Precautions

MA1002A accelerometer is encapsulated in a hermetic ceramic housing to protect the sensor from the ambient environment. However, poor handling of the product can induce damage to the hermetic seal (Glass frit) or to the ceramic package made of brittle material (alumina). It can also induce internal damage to the MEMS accelerometer that may not be visible and cause electrical failure or reliability issues. Handle the component with caution: shocks, such as dropping the accelerometer on hard surface, may damage the product.

The component is susceptible to damage due to electrostatic discharge (ESD). Therefore, suitable precautions shall be employed during all phases of manufacturing, testing, packaging, shipment and handling.

Accelerometer will be supplied in antistatic bag with ESD warning label and they should be left in this

packaging until use. The following guidelines are recommended:

- Always manipulate the devices in an ESD-controlled environment
- Always store the devices in a shielded environment that protects against ESD damage (at minimum
- an ESD-safe tray and an antistatic bag)
- Always wear a wrist strap when handling the devices and use ESD-safe gloves

ESD caution

This product can be damaged by electrostatic discharge (ESD). Handle with appropriate precautions.

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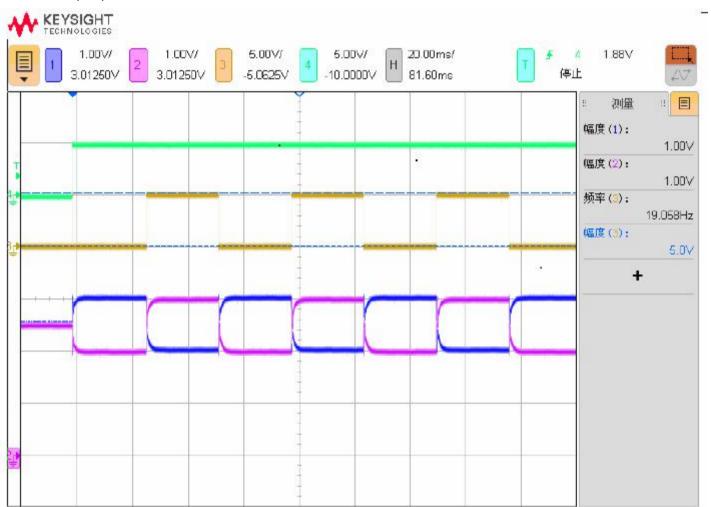
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Self-test Function

MA1002A accelerometer has self test function. During self test, pull up STEN (pin 11) voltage into 5V. In self test mode, if the accelerometer works normally, self test output pin ERR and differential output pin OUTP/OUTN will output around 19Hz periodic square wave signal, see as following picture. In other mode, self test output pin ERR will be low level.



Channel 1: OUTP, Channel 2: OUTN, Channel 3: ERR, Channel 4: STEN

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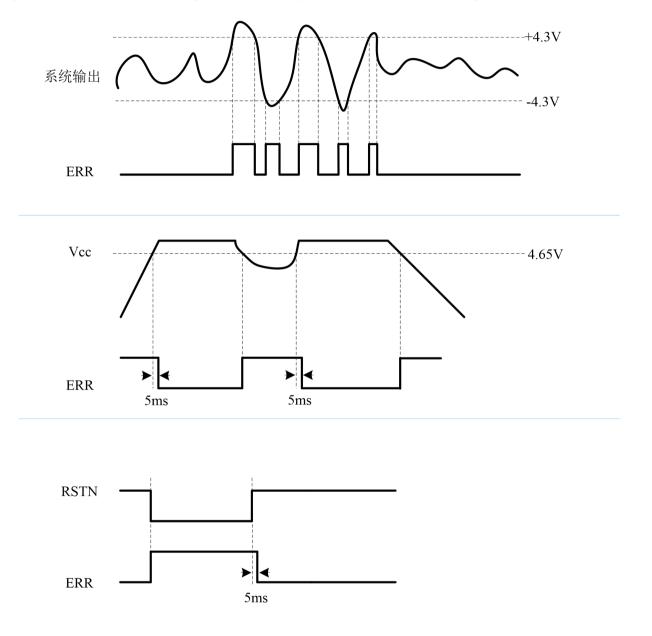
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Fault Report Function

MA1002A accelerometer has fault report function. If there is overload during working, and the power supply is lower than 4.65V or the accelerometer is under resetting, the output of ERR pin will pull up, which means that the system has fault. the following picture is the system fault report function graph.



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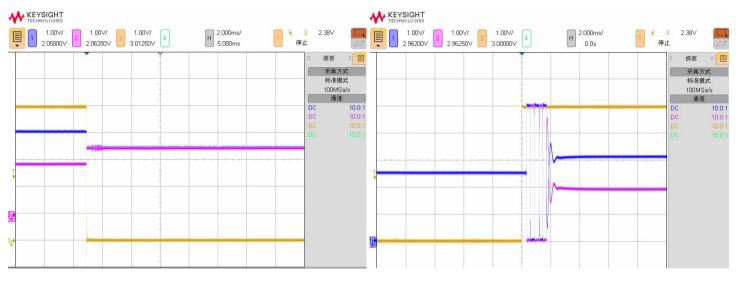
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Reset Function

MA1002A accelerometer has reset function. During reset, pull down RSTN (pin 12). In reset mode, the accelerometer output (OUTP, OUTN): differential mode is 0, and common mode is 2.5V. After cancelling reset, the accelerometer output will enter stable working status after 4ms. the following picture is the output wave graph under reset mode (the accelerometer in the picture is in 1g status).



Channel 1: OUTP, Channel 2: OUTN, Channel 3: RSTN

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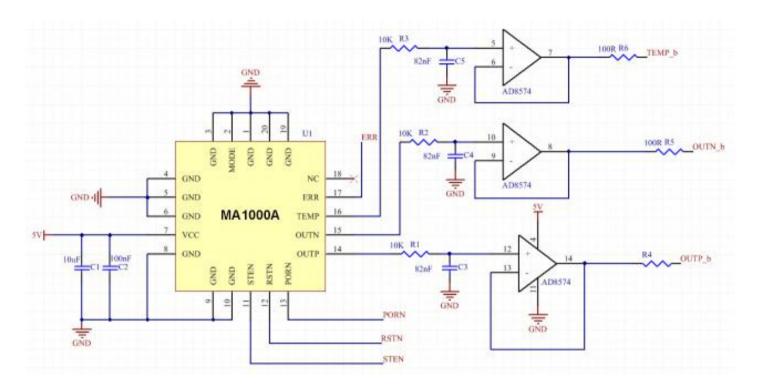
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Recommended Circuit

In order to obtain the best MA1002A accelerometer, please use MA1002A accelerometer according to the following application circuit.



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Soldering Method

MA1002A accelerometer is high precise MEMS accelerometer, in order to keep MA1002A excellent working performance and reliability, please pay attention during soldering; put the component in stable, don't vibrate it, and assure every pin to be soldered well, and make the component parallelled with the application circuit, and make the whole accelerometer bear averaged force.

MA1002A is suitable for Sn/Pb and Pb-Free soldering and ROHS compliant. the melting point can't be higher than 220°C

the recommened typical temperature profiles settings are as fillows:

Prehear--temperature: normal temperature~145°C, ramp-up of 1~2°C/second;

Fusion--temperature: 145~165°C, duration: 100seconds;

Peak--temperature: 220°C, duration: 45seconds;

Cold--temperature: 220°C~normal temperature, ramp-down: natural temperature reduction;

In actual usage, the above parameters can be adjustable according to the selected solder maternial (the peak temperature can't exceed 220°C

The cleaning process of electronic boards sometimes involves ultrasounds. This is strongly prohibited on our sensors. Ultrasonic cleaning will have a negative impact on silicon elements which generally causes damages.



Forbidden Ultrasonic Cleaning

Note: Ultrasonic cleaning is forbidden in order to avoid damage of the MEMS accelerometer

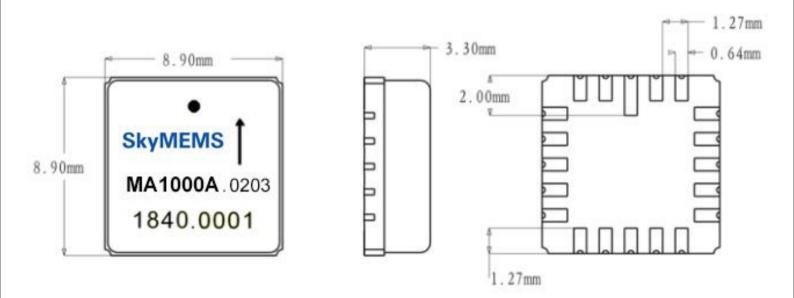
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Dimension & Package



MA1002A Package						
Parameter	Comments	Min	Typical	Мах	Unit	
Lead Finishing	Au plating	0.5	-	-	um	
	Ni Plating	2	-	-	um	
	W (tungsten)	16	-	-	um	
Weight		0.63	0.639	0.645	grams	
Size	Х	8.95	9	9.07	mm	
	Y	8.92	9.01	9.1	mm	
	Z	3.3	3.38	3.45	mm	
Packaging	LCC20 pin housing					
Proximity effect	The sensor is sensitive to external parasitic capacitance. Moving metallic objects with large mass or parasitic effect in close proximity of the accelerometer (mm range) must be avoided to ensure best product performances. A ground plane below the accelerometer is recommended as a shielding.					
Reference plane for axis alignment	LCC must be tightly fixed to the circuit board, using the bottom of the housing as the reference plane for axis alignment. Using the lid as reference plane or for assembly may affect specifications and product reliability (i.e. axis alignment and/or lid soldering integrity)					

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