

MG100 Single Axis MEMS Gyro



- Cost Effective Z Axis MEMS Gyro
- Heading: diverging 0.1°/hour
- Range: gyro ±300° /s, (ODM supported)
- Wide Input Power Range: 6~14VDC
- Compact and Lightweight 50 x 45 x 21 (mm), 70g
- Wide Working Temperature: -40° C~+85° C







Product Description

MG100 Single Axis MEMS Gyro is Z axis MEMS gyro system, which provides accurate heading direction, MG100 is a miniature factory-calibrated module to provide consistent performance through the extreme operating environments.

MG100 offers a highly-effective solution for cost-sensitive demanding applications. It adopts advanced MEMS components, which reduces the cost deeply. The system enjoys small size and light weight, it is widely applied in Robotics Control, Platform Stabilization, Antenna Stabilization, etc.

- 12-Step Quality Control, Higher Reliability, More **Functions**
- ✓ Adopting Original Big Brand Component, High-class Glue Encapsulation
- ✓ Real Actual Precise after Calibration, Perfect Performance
- ✓ Successful Applications in Tens of Fields, More than 1000 Customers are Using

Typical Applications



Robot Control



Antenna Stabilization



Industrial Control



AGV

Focus on MEMS Measurement & Control Technologies, Products includ

VG

MEMS Acc MEMS Gyro AHRS

Inclinometer MRU

E-compass

IMU **GNSS/INS**



MG100 Single Axis MEMS Gyro

Technical Specs

Technical Specs					
Parameter	Value	Comments			
Heading					
Range	±180°				
Accuracy	0.1°/hour	it is diverging with time, diverging speed is 0.1°/hour			
Gyro					
Range: Heading	$\pm 300^{\circ}$ /s $\pm 75^{\circ}$ /s, $\pm 150^{\circ}$ /s, $\pm 900^{\circ}$ /s	default setting optional			
Noise	< 0.3°/s(RMS)				
Zero Error (25° C)	< 0.2°/s				
Bias Instability	24°/h (75°/s range) 40°/h (900°/s range)	typical value, Allen Variance			
Bias Temperature Error	$\pm 3^{\circ}$ /s				
Zero Drift Repeatability	0.14°/s(RMS)				
Scale Factor Non-linearity	0.2%				
Bias Acceleration Sensitivity	0.077°/s/g (typical) 0.17°/s/g (max)				
Rate Noise Density	0.025°/s/sqrHz				
Angle Random Walk Coefficient	0.28°/h	Allen Variance			
Bias Vibration Sensitivity	0.001°/s/g2rms (typical) 0.003°/s/g2rms (max)	12g (RMS), 10Hz ~5kHz, random			
Bandwidth	5~160Hz				

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MEMS Gyro Inclinometer E-compass IMU



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Technical Specs

Technical Specs				
Parameter	Value	Comments		
Environment Condition				
Working Temperature	-40~+85°C			
Protection Level	IP66			
Electromagnetic compatibility	Compatible with EN61000 and GBT17626			
MTBF	≥5000hours			
Vibration Resistance	10grms, 10~1000Hz			
Shock Resistance	100g@11ms, 3 axes, (half sine wave)			
Power Supply				
Input Voltage	6~14VDC			
Current	60mA@9VDC			
Communication Protocol				
Default Interface	RS232			
Baud rate	115200			
Data Update Rate	100Hz			
Physical Parameter				
Dimension	50mm*45mm*21mm			
Weight	around 70 grams			
Connector	5 pin mini aviation connector			
Location Hole	4 holes			

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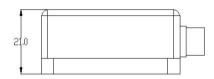


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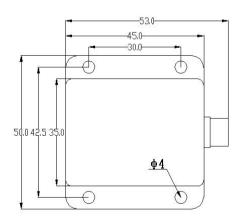
Pins Definition

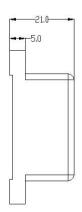
Pins Definition				
Pins No.	5 pin mini aviation connector Line Color	Name	Description	
1	Brown	Vcc	power positive pole	
2	Black	GND	power gound	
3	White	RS232_TX	RS232 data transmitting	
4	Blue	RS232_RX	RS232 data receiving	
5	Gray	RS232_GND	RS232 signal ground (short circuit with power ground inside the sensor)	

Dimension & Package



(Unit: mm)





MG100 three-view drawing

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Com Protocol

the electronic parameters of RS232 communication protocol are as follows:

➤ Baud rate: 115200

Data bit: 8 > Stop bit: 1

> Check bit: none

the data string is sent out every 10ms, and each data string includes 58 bytes, the detailed description see as follows:

Data String Definition				
Name	Byte Length	Description		
Initial Code	4	0x4E 0x4A 0x35 0x92		
X axis of acceleromter	4	0		
Y axis of acceleromter	4	0		
Z axis of acceleromter	4	0		
X axis of gyro	4	0		
Y axis of gyro	4	0		
Z axis of gyro	4	float mode floating number, 4 bytes, high byte in front, unit:deg/s		
X axis of magnetic sensor	4	0		
Y axis of magnetic sensor	4	0		
Z axis of magnetic sensor	4	0		
Temperature	4	float mode floating number, 4 bytes, high byte in front, unit: °C		
Heading Angle (divergence)	4	float mode floating number, 4 bytes, high byte in front, unit:deg		
Roll Angle	4	0		
Pitch Angle	4	0		
Sum Check	2	high byte in front, low byte in behind, the sum of all the front data		

Remarks: during turning on the sensor, please keep the sensor in static status, and after turning on the sensor, please keep the sensor in statis status more than 5 seconds

> **MEMS Acc MEMS Gyro AHRS**

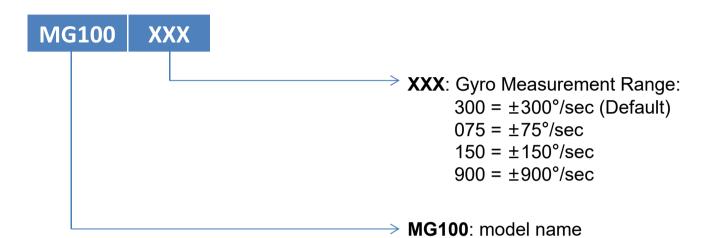
Inclinometer **MRU**

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Order Information



For example, MG100-900 means that the MG100 with 1 axis gyro range: ±900°/sec

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