

# MGA1000

## High Performance Single Axis Gyro with Triaxial Accelerometers



### Main Features

- Cost Effective Z Axis MEMS Gyro with 3 Accelerometers
- Heading: Diverging 0.5° /hour
- Range: Acc  $\pm 2g$ , Gyro  $\pm 300^\circ /s$ , (ODM Supported)
- Fully Calibrated and Error Compensation
- Wide Input Power Range: 5~24VDC
- High Survivability in Harsh Environment, IP67
- Compact and Lightweight - 50 x 45 x 21mm, 70grams
- Wide Working Temperature:  $-40^\circ C \sim +85^\circ C$

MGA1000 Single Axis MEMS Gyro with Triaxial Accelerometer is composed of one Z axis MEMS gyro and 3 accelerometers, which provides accurate heading direction and accelerations, MGA1000 is a miniature factory-calibrated module to provide consistent performance through the extreme operating environments.

MGA1000 offers a highly-effective solution for cost-sensitive demanding applications. It adopts advanced MEMS components, which reduces the cost deeply. The system enjoys small size and light weight, it is widely applied in AGV, Robotics Control, Platform Stabilization, etc.

- ✓ 12-Step Quality Control, Super Reliability, More Functions
- ✓ Adopting Original Big Brand Component, High-class Material, Competitive Price

- ✓ Real Actual Precise after Calibration, Perfect Performance
- ✓ Successful Applications in Tens of Fields, More than 1000 Customers are Using

## Typical Applications



AGV



Robot



Industries



Platform Stability

### Super Reliability & Performance

[www.SkyMEMS.com](http://www.SkyMEMS.com) Mobile: +86 133 7203 8516  
Skype: skymems

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Focus on MEMS Measurement & Control Technologies, Products include:

MEMS Acc	MEMS Gyro	IMU	Vertical Gyro	AHRS
INS	GNSS/INS	E-compass	Inclinometer	FOG

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## High Performance Single Axis Gyro with Triaxial Accelerometers

### Technical Specifications

Technical Specs		
Parameter	Value	Comments
<b>Heading</b>		
Range	±180°	
Accuracy	0.5°/hour	it is diverging with time, diverging speed is 0.5°/hour
Resolution	0.01°	
<b>Gyro</b>		
Range: Heading	±300°/s	
Noise	< 0.05°/s(RMS)	
Zero Error (25°C)	< 0.05°/s	
Zero Bias Drift	<0.5°/h	
Zero Drift Repeatability	<0.05°/s	
Scale Factor Non-linearity	0.2%	
<b>Accelerometer</b>		
Range: X, Y, Z	±2g	±6g optional
Non-linearity	0.5%	
Noise	400ug/√Hz	

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### Technical Specifications

Technical Specs		
Parameter	Value	Comments
<b>Environment Condition</b>		
Working Temperature	-40~+85°C	
Protection Level	IP67	
Electromagnetic compatibility	Compatible with EN61000 and GBT17626	
MTBF	≥5000hours	
Vibration Resistance	10grms, 10~1000Hz	
Shock Resistance	100g@11ms, 3 axes, (half sine wave)	
<b>Power Supply</b>		
Input Voltage	5~24VDC	
Current	50mA@9VDC	
<b>Communication Protocol</b>		
Default Interface	RS232	RS485, CAN optional
Baud rate	115200	
Data Update Rate	100Hz	
<b>Physical Parameter</b>		
Dimension	50mm*45mm*21mm	
Weight	around 70 grams	
Connector	5 pin mini aviation connector	
Location Hole	4 holes	

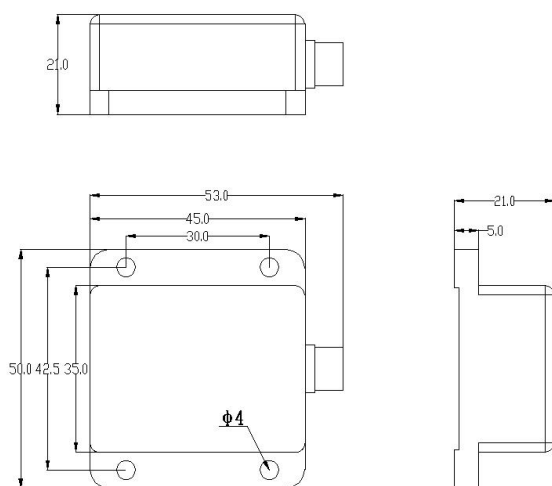
# MGA1000

## High Performance Single Axis Gyro with Triaxial Accelerometers

### Pins Definition

Pins Definition		
Pins Line Color	Name	Description
CAN output		
Red	VCC	power positive pole
Black	GND	power ground
Brown	CAN_H	CAN interface H
Green	CAN_L	CAN interface L
RS232 Output		
Brown	VCC	power positive pole (5~24VDC)
Black	GND	power ground
White	RS232_TX	RS232 data transmitting
Blue	RS232_RX	RS232 data receiving
Gray	RS232_GND	RS232 signal ground (short circuit with power ground inside the sensor)
RS485 Output		
Brown	VCC	power positive pole (5~24VDC)
Black	GND	power ground
White	RS485_A	RS485A
Blue	RS485_B	RS485B

### Dimension & Package



(Unit: mm)

MGA1000 three-view drawing

### Super Reliability & Performance

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### Communication Protocol

#### 1. RS232, RS485 communication protocol:

- Baud rate: 115200
- Data bit: 8
- Stop bit: 1
- Check bit: none

#### 2. CAN:

- Baud rate: 250K
- Format: standard frame (ID: 0x146)

Remarks: CAN output settings can be modified according to customer's requirements, the above setting is default settings.)

#### 3. MGA1000 output communication protocol:

the data string is sent out every 10ms, and each data string includes 58 bytes, the detailed description see as follows:

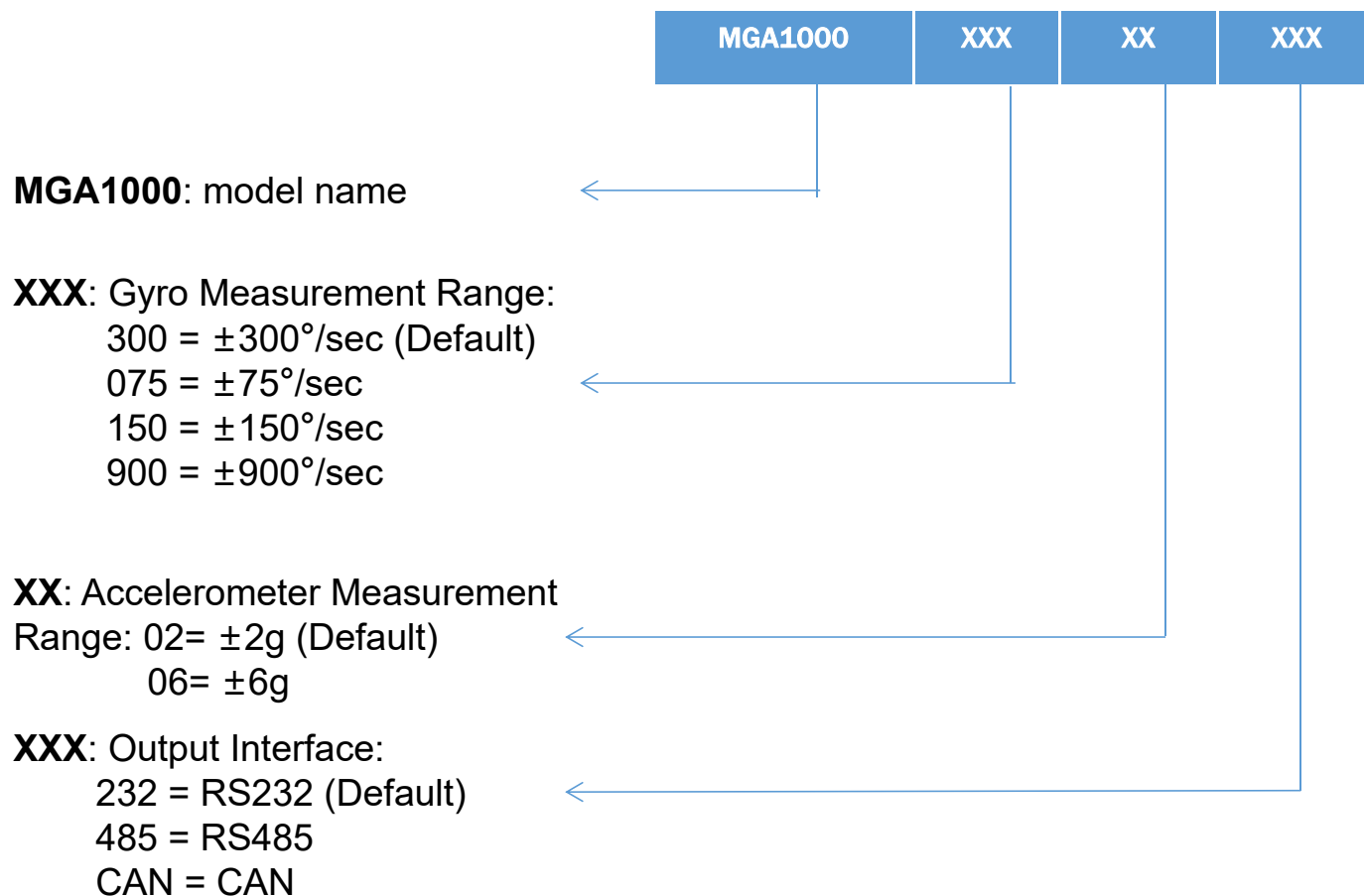
Data String Definition		
Name	Byte Length	Description
Initial Code	4	0x4E 0x4A 0x35 0x94
X axis of accelerometer	4	float mode floating number, 4 bytes, high byte in front, unit: g
Y axis of accelerometer	4	float mode floating number, 4 bytes, high byte in front, unit: g
Z axis of accelerometer	4	float mode floating number, 4 bytes, high byte in front, unit: g
X axis of gyro	4	0
Y axis of gyro	4	0
Z axis of gyro	4	float mode floating number, 4 bytes, high byte in front, unit:deg/s
X axis of magnetic sensor	4	0
Y axis of magnetic sensor	4	0
Z axis of magnetic sensor	4	0
Temperature	4	float mode floating number, 4 bytes, high byte in front, unit: °C
Heading Angle (divergence)	4	float mode floating number, 4 bytes, high byte in front, unit:deg
Roll Angle	4	0
Pitch Angle	4	0
Sum Check	2	high byte in front, low byte in behind, the sum of all the front data

Remarks: during turning on the sensor, please keep the sensor in static status, and after turning on the sensor, please keep the sensor in static status more than 5 seconds

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### Order Information



For example, MGA1000-300-02-232 means that the MGA1000 with 1 axis gyro range: ±300°/sec, accelerometer range: ±2g, with RS232 output interface.